PFC-DCM TDA4817

Power Factor Controller
IC for Higher Power Factor and
Active Harmonic Filtering

Power Management & Supply



TDA4817 Revision History: 1995-05-01 Datasheet Previous Version: Page Subjects (major changes since last revision)

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Power Factor Controller

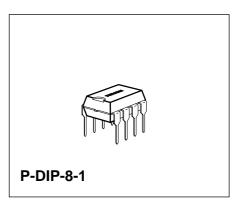
TDA 4817

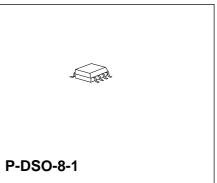
IC for High Power Factor and Active Harmonic Filtering

Advance Information Bipolar IC

Features

- IC for sinusoidal line-current consumption
- Power factor approaching 1
- Controls boost converter as an active harmonics filter
- Direct drive of SIPMOS transistor
- Zero crossing detector for discontinuous operation mode with variable frequency
- 110/220 V AC operation without switchover
- Standby current consumption of 0.5 mA





	Туре	Ordering Code	Package		
▼	TDA 4817	Q67000-A8298	P-DIP-8-1		
\blacksquare	TDA 4817 G	Q67000-A8299	P-DSO-8-1 (SMD)		



The TDA 4817 contains all functions for designing electronic ballasts and switched-mode power supplies with sinusoidal line current consumption and a power factor approaching 1.

The TDA 4817 controls a boost converter as an active harmonic filter in a discontinuous (triangular shaped current) mode with variable frequency.

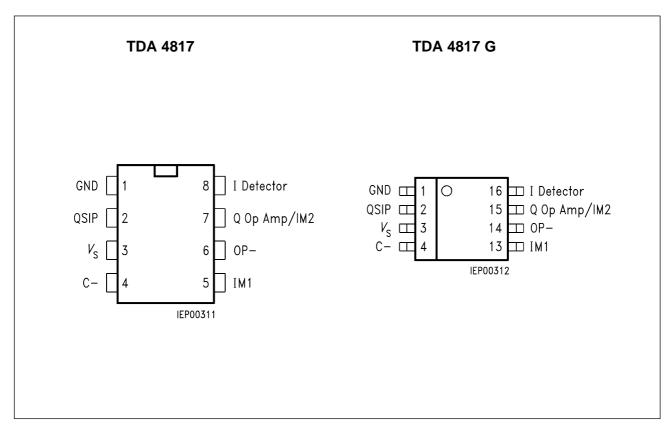
A typical application is in electronic ballasts, especially when a large number of such lamps are concentrated on one line supply point.

The output voltage of this filter is regulated with high efficiency. Therefore the device can be easily operated on different line voltages (110/220 V_{AC}) without any switchover.

The TDA 4817 is an 8-pin-economy-version of the TDA 4814 A without reference voltage output and start/stop monitoring circuit.

Version 2.0 3 1 May 1995





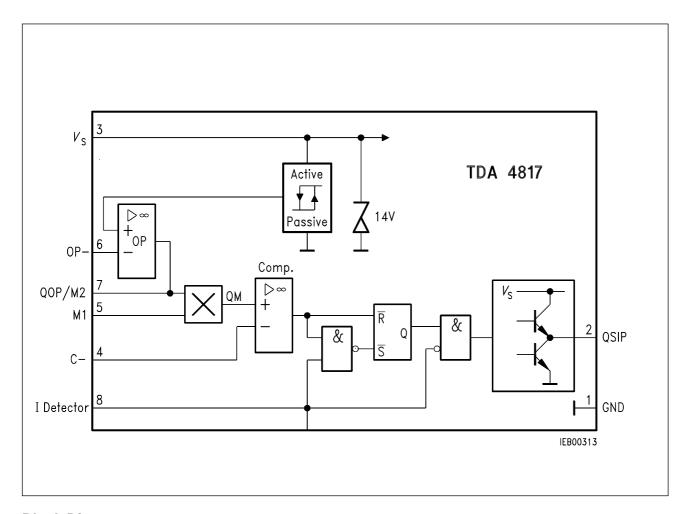
Pin Configurations

(top view)

Pin Definitions and Functions

Pin	Symbol	Function
1	GND	Ground
2	QSIP	Driver output
3	V_{S}	Supply voltage
4	C –	Comparator input
5	IM1	Multiplier input
6	OP –	Input
7	QOP/IM2	Operational-amplifier output QOP and multiplier input M2
8	I Detector	Detector input





Block Diagram



Circuit Description

This device has a conditioning circuit for the internal power supply. It allows standby operation with very low current consumption (less than 0.5 mA), a hysteresis between enable and switch-off levels and an internal voltage stabilization. An integrated Z-diode limits the voltage on $V_{\rm S}$, when impressed current is fed.

The **output driver (Q SIP)** is controlled by detector input and current comparator.

The **detector input (I DET)** which is highly resistive in the operating state reacts on hysteresisdetermined voltage levels. To keep down the amount of circuitry required, clamping diodes are provided which allow control by a current source.

The operating state of the boost converter choke is sensed via the detector input. H-level means that the choke discharges and the output driver is inhibited. H-level sets a flip-flop, which stores the switch-off instruction of the current comparator to reduce susceptibility to interference. As soon as demagnetization is finished the choke voltage reverses and the detector input is set to L-level, thus enabling the output driver. This ensures that the choke is always currentless when the SIPMOS transistor switches on and that no current gaps appear.

The nominal voltage of the multiplier output is compared to the voltage derived from the actual line current (— I COMP), thus setting the switch-off threshold of the comparator. The current comparator blocks the output driver when the nominal peak value of the choke current given by the multiplier output is reached.

This state is maintained in the flip-flop until H-level appears at detector input which takes over the hold function and resets the flip-flop.

Operating states might occur without any useful detector signal. This is the case with magnetic saturation of the choke and when the input voltage approaches or exceeds the output voltage as, for example, during switch-on. The driver remains inhibited for the flip-flop due to the absent set signal.

The trigger signal can be derived from the subsequent lamp generator or a SMPS control device. The trigger signal level should be so low that with standard operation the signal from the detector winding dominates. The multiplier delivers the preset nominal value for the current comparator by multiplying the input voltage (IM1), which determines the nominal waveform and the output voltage of the control amplifier.

The control amplifier stabilizes the output dc voltage of the active harmonic filter in the event of load and input voltage changes. The **control amplifier** compares the actual output voltage to a reference voltage which is provided in the IC and stable with temperature.

Output Driver

The output driver is intended to drive a SIPMOS transistor directly.

It is designed as a push-pull stage.

Both the capacitive input impedance and keeping the gate level at zero potential in standby operation by an internal $10-k\Omega$ -resistor are taken into account. Possible effects on the output driver by line inductances or capacitive couplings via SIPMOS transistor Miller capacitance are limited by diodes connected to ground and supply voltage.



Absolute Maximum Ratings

Parameter		Symbol	Limit Values			Unit	Remarks
			min. typ.		max.		
Supply voltage		V_{S}	- 0.3		V_{Z}	V	$V_{\rm Z}$ = Z-voltage
Inputs		V _C –	- 0.3		20	V	
Comparator		V_{OP} –	- 0.3		20	V	
Operational a Multiplier	mplifier	V_{M1}	- 0.3		20	V	
Output OP		V_{QOP}	- 0.3		6	V	
Z-current V _s -GND		I_{Z}	0		100	mA	Observe P_{max}
Driver output QSIP		V_{QSIP}	- 0.3		Vs	V	
QSIP clamping diodes		I_{QSIP}	- 10		10	mA	$V_{\rm QSIP} > V_{\rm S}$ or $V_{\rm QSIP} < -0.3 \text{ V}$
Detector input		V_{Det}	0.9		6	V	
Detector clamping diodes		I_{Det}	- 10		10	mA	V_{Det} > 6 V or V_{Det} < 0.9 V
Junction temperature		$T_{\rm j}$			150	°C	
Storage temperature		$T_{ m stg}$	- 55		125	°C	
Thermal resistance	ce						
system-air	TDA 4817	R_{thSA}			100	K/W	P-DIP-8 package
	TDA 4817 G	R_{thSA}			170	K/W	P-DSO-8 package

Operating Range

Supply voltage	$V_{\mathtt{S}}$	V_{Son}	V_{Z}	V	1)
Z-current	I_{Z}	0	100	mA	Observe P_{max}
Driver current	I_{QSIP}	- 500	500	mA	Observe P_{max}
Ambient temperature	T_{A}	- 25	85	°C	



Characteristics

 $V_{\rm SON}$ < $V_{\rm S}$ < $V_{\rm Z};~T_{\rm A}$ = - 25 to 85 $^{\circ}{\rm C}$

Parameter	Symbol		Limit Val	ues	Unit	Test Condition
		min.	typ.	max.		
Current Consumption		•	·	•	·	
Without load on driver (QSIP) and $V_{\rm REF}$; QSIP low Load on QSIP with SIPMOS gate; dynamic operation	I _S I _S I _S		5	0.5 10 15	mA mA mA	$\begin{array}{c} 0~\mathrm{V} < V_{\mathrm{S}} < V_{\mathrm{SON}} \\ V_{\mathrm{SON}} < V_{\mathrm{S}} < V_{\mathrm{Z}} \\ V_{\mathrm{S}} = 12~\mathrm{V}; \\ f_{\mathrm{switch}} = 50~\mathrm{kHz}; \\ \mathrm{load~QSIP} = 10~\mathrm{nf} \end{array}$
Hysteresis on V_{S}						
Turn-ON threshold for $V_{\rm S}$ rising Switching hysteresis	$V_{SH} \ V_{Shy}$	9.6 1.0	10.4	11.2 1.7	V	
Comparator						
Input offset voltage Input current Common-mode input	$V_{\rm IO} - I_{ m I}$	- 10		10 2	mV μA	
voltage	$V_{ m ICM}$	0		3.5	V	
Operational Amplifier						
Open-loop voltage gain Input offset voltage Input current Common-mode input	$G_{ m VO} \ V_{ m IO} \ -I_{ m I}$	60 - 10	80	10 2	dB mV μA	
voltage Output current Output voltage Gain-bandwidth product Transition phase Voltage Feedback	$V_{ ext{IC}}$ $I_{ ext{Q}}$ $V_{ ext{Q}}$ $f_{ ext{r}}$	0 -3 1.2	2 120	3.5 1.5 4	V mA V MHz deg	
Threshold	V_{FB}	1.96	2	2.04	V	$T_{\rm j}$ = 25 °C Pin 6 connected to Pin 7
Temperature response	$\Delta V_{ extsf{FB}}/\Delta T$	- 0.3		0.3	mV/K	
Output Driver			•	•		
H-output voltage L-output voltage Output current rising edge falling edge	$V_{ m QSIPH} \ V_{ m QSIPL} \ -I_{ m QSIP} \ I_{ m QSIP}$	5 200 250	300 350	1 400 450	V V mA mA	I_{QSIP} = $-$ 10 mA I_{QSIP} = 10 mA C_{L} = 10 nF C_{L} = 10 nF



Characteristics (cont'd)

 $V_{\rm SON}$ < $V_{\rm S}$ < $V_{\rm Z};~T_{\rm A}$ = - 25 to 85 $^{\circ}{\rm C}$

Parameter		Symbol		Limit Valu	ues	Unit	Test Condition	
			min. typ.		max.			
Z-Diode (V _s)					-	•	-1	
Z-voltage (obser	ve P_{max})	V_{Z}	13	15.5	17	V	$I_{\rm Z}$ = 200 mA	
Multiplier						•		
Quadrant for inp	ut			1.		qu		
voltages Input voltage M1		V_{M1}	0		2	V		
Reference level		V_{REFM1}		0		V		
Input voltage M2	_	V_{M2}	V_{REF}		V_{REF} + 1	v		
Reference level		V_{REFM2}	, KEF	V_{REF}	, KEF	V		
Input current M1	_	$-I_1$	0	, KEF	2	μA		
Max. output volta	•	V_{QMmax}		1.6		v		
Multiplier gain	Ü	C_{Q25}	0.62	0.67	0.72	V-1	$T_{\rm i}$ = 25 °C ¹⁾	
Multiplier gain		C_{Q}	0.55		0.77	V-1	1)	
Temperature res	ponse	$\Delta TC/C_Q$	- 0.3	- 0.1	0.1	%/K		
of coefficient								
Delay Times								
Input comparato	r-QSIP	t_1		500	700	ns	2)	
Detector				·				
Upper switching	voltage							
for voltage rising (H)		V_{DetH}	1.0	1.3	1.6	V		
Lower switching voltage								
for voltage falling (L)		V_{DetL}	0.95			V		
Input current		$-I_{Det}$			10	μΑ	$0.9 \text{ V} < V_{\text{Det}} < 6 \text{ V}$	
Clamping-diode								
level	positive	V_{Det} +		6.9		V	$I_{\text{Det}} = 3 \text{ mA}$	
0 11 11	negative	$V_{Det}-$		0.6	000	,,,	$I_{\rm Det}$ = 3 mA	
Switching hysteresis		V_{Dethy}	50		300	mV		

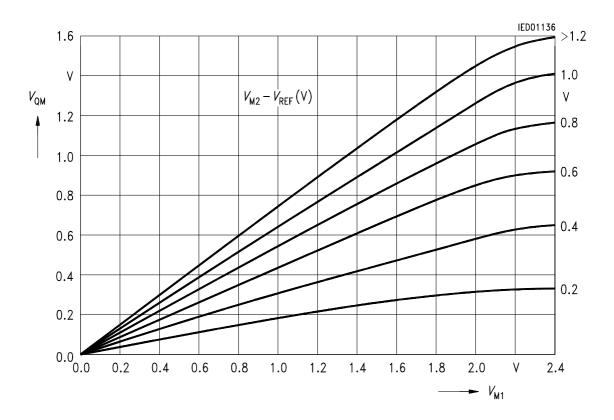
Calculation of output voltage $V_{\rm QM}$: $V_{\rm QM}$ = C x $V_{\rm M1}$ x $V_{\rm M2}$ in V.

1)
$$V_{\rm M1}$$
 = 1 V $V_{\rm M2}$ = $V_{\rm REF}$ + 1 V

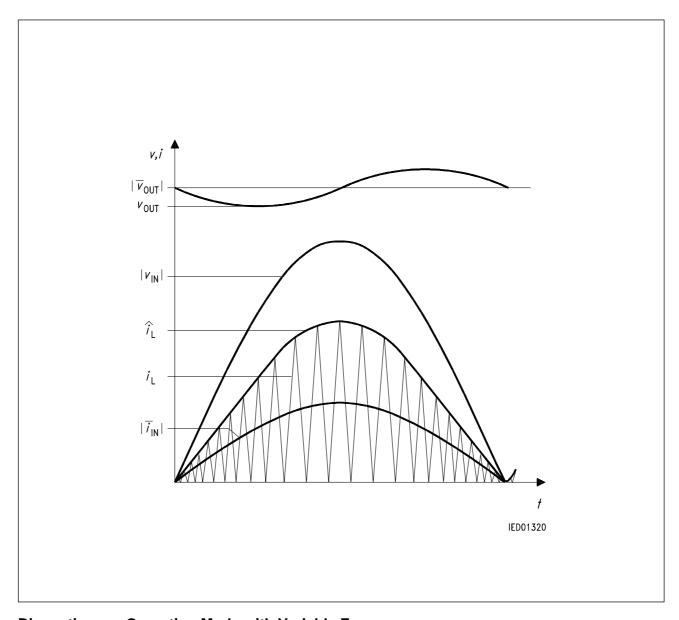
2) Step function on comparator input $\Delta V_{\rm Comp}$ from – 100 mV to + 100 mV.



Multiplier Characteristics







Discontinuous Operation Mode with Variable Frequency

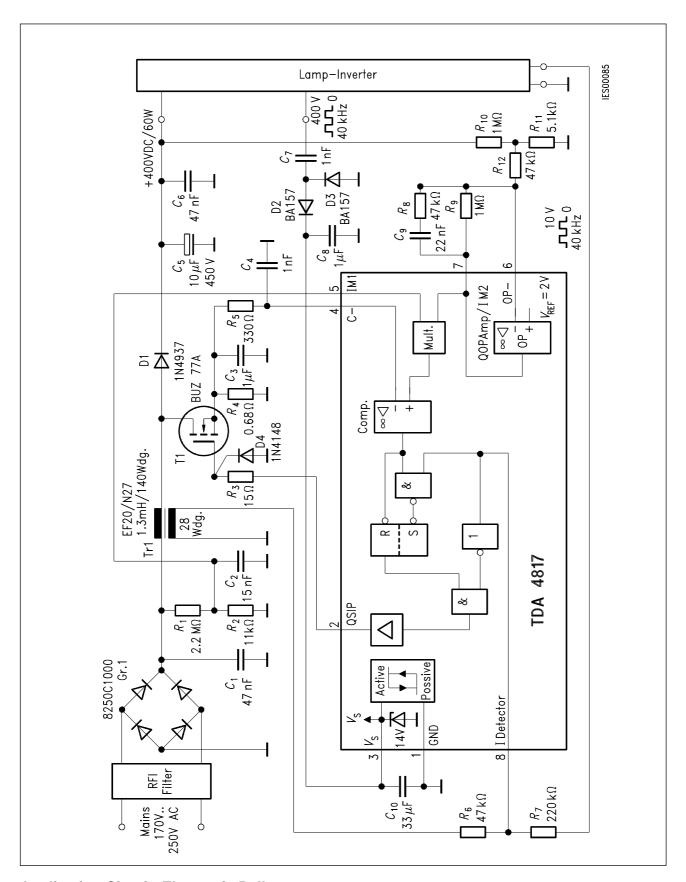
The TDA 4817 works in a discontinuous operation mode with variable frequency.

The principle of a freely oscillating controller exploits the physical relationship between current and voltage at the boost converter choke. The current in the semiconductors flows in a triangular shape. This is only when the current in the boost converter diode has gone to zero that the transistor goes conductive. This arrangement does away with the diode's power-squandering reverse currents.

If triangular currents flow continuously through the boost converter choke the input current averaged over a high-frequency period is exactly half the peak of the high-frequency choke current.

If the peak values of the choke current are located along an envelope curve that is proportional to a sinusoidal low-frequency input voltage, the input current available after smoothing in an RFI filter is sinusoidal.





Application Circuit: Electronic Ballast



The TDA 4817 controls a boost converter as an active harmonic filter, drawing a sinusoidal line current and providing a regulated DC voltage at the converter output.

The active harmonic filter improves the power factor in electronic ballasts for fluorescent lamps and in switched-mode power supplies, reducing the harmonic content of the incoming, non rectified mains current and if suitably dimensioned permitting operation at input voltages between 90 V and 270 V.

Benefits of TDA 4817 in Electronic Ballasts and SMPS

- Sinusoidal line current consumption
- Power factor approaching 1 increases the power available from the AC line by more than 35 % compared to conventional rectifier circuits. Circuit breakers and connectors become more reliable because of the lower peak currents.
- Active harmonic filtering reduces harmonic content in line current to meet VDE/IEC/ENstandards.
- Wide-range power supplies are easier to implement for AC input voltages of 90 to 250 V without switch-over.
- Preregulated DC output voltage provides optimal operating conditions for a subsequent converter.
- Reduced smoothing capacitance:

For a given amplitude of the 100/120 Hz ripple voltage the smoothing capacitance can be reduced by 50 % in comparison to a conventional rectifier circuit.

Reduced choke size:

Rectifier circuits capable of more than 200 W usually employ chokes to decrease the charging current of the capacitor. These chokes are larger than those used in a preregulator with power-factor control.

Higher efficiency:

A preregulator does cause some additional losses, but these are more than compensated for by the cut in losses created by the rectifier configuration and the optimum operating conditions that are produced for a subsequent converter, even in the event of supply-voltage fluctuations.



Summary of Effects of DC-Voltage Preregulation with Power-Factor Control

Parameter	Conventional Power Rectification	Power Rectification with Preregulator and Power-Factor Control
Mean DC supply voltage	280 V	340 V
Maximum DC supply voltage with line overvoltage	350 V	350 V
Minimurn DC supply voltage with line undervoltage	230 V	330 V
Relative reverse voltage of diodes with line overvoltage	1	0.7
Relative forward resistance of SIPMOS transistors with sustained conducting-state power loss and line undervoltage	1	2.06
Relative forward resistance of SIPMOS transistors with sustained conducting-state power loss and rated supply voltage		1.74
Relative input capacitance with sustained ripple voltage	1	0.3 to 0.5
Power factor	0.5 to 0.7	0.99

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